

Sticky Information and the Taylor Principle

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Motivation and Contribution

This paper presents **determinacy bounds** on monetary policy for the **sticky information model** (Mankiw and Reis, 2002)

- Determinacy bounds on monetary policy previously **unobtainable**
 - Existing analysis relies on **time domain** methods that only approximate the solution
 - We provide **frequency domain methods** that provide closed form results
 - **New insights** into dynamics and bounds on monetary policy
- ⇒ These facts are at odds with standard textbook macro models!
 ⇒ How can we overcome these challenges?

Our contribution: use **frequency domain methods** that enable **closed form** and **conservative restrictions** on monetary policy rules in the absence of model certainty:

Sticky Information and the Taylor Principle

The **Sticky Information model in the frequency domain:**

- ... derives a fully recursive expression of the sticky information Phillips curve
- ... finds determinacy bounds on monetary policy previously unobtainable
- ... remains analytically tractable
- ... gives new insights in model dynamics

The z-transform

Consider the unilateral square-summable sequence of real numbers

$$\{c_j\}_{j=0}^{\infty}$$

where $c_j \in \mathbb{R}$ such that $\sum_{n=0}^{\infty} c_n^2 < \infty$.

Then, the well-defined random variable is a function of the underlying shocks:

$$x_t = \sum_{j=0}^{\infty} c_j \epsilon_{t-j} = \sum_{j=0}^{\infty} c_j L^j \epsilon_t = c(L) \epsilon_t$$

The **z-transform** of the sequence c_j is then given by the following function

$$x(z) = \sum_{j=0}^{\infty} c_j z^j$$

where $z \in \mathbb{C}$ and $z = e^{i\omega}$ for the angular frequency $\omega \in [-\pi, \pi]$. Scaling in the z domain connects initial conditions, unconditional moments and dampening

$$x(\lambda z) = \sum_{j=0}^{\infty} \lambda^j c_j z^j, \quad x(0) = c_0 \quad \text{IFFT}(x(z^{-1}) \sigma_\epsilon^2 x(z))|_{|z|=1} = \sigma_\epsilon^2$$

For $0 < \lambda < 1$, more distant (lower frequency) movements' contribution to moments reduced

Sticky Information versus Sticky Prices

Sticky Price Phillips Curve:

$$\pi_t = \beta E_t \pi_{t+1} + \kappa y_t$$

Sticky Information Phillips Curve:

$$\pi_t = \frac{1-\lambda}{\lambda} \xi y_t + (1-\lambda) \sum_{i=0}^{\infty} \lambda^i E_{t-i-1} [\pi_t + \xi (y_t - y_{t-1})]$$

$\xi > 0$ degree of strategic comp., and $0 < 1 - \lambda < 1$ is the prob. of an info update.

Inflation depends on output, **past expectations** of current inflation and output growth

Standard Dynamic IS Demand:

$$y_t = E_t y_{t+1} - \sigma R_t + \sigma E_t \pi_{t+1}$$

Monetary policy

$$R_t = \phi_\pi \pi_t + \phi_y y_t$$

The **infinite regress of lagged expectations** precludes a **recursive** representation in the time domain. Therefore we express the model in the frequency domain.

Recursive Frequency Domain Representation

Sticky Price Phillips curve in the Frequency Domain:

$$\pi(z) = \beta \frac{1}{z} (\pi(z) - \pi_0) + \kappa y(z)$$

Sticky Information Phillips curve in the Frequency Domain:

$$y(z) = \frac{\lambda}{\xi} \frac{1}{1-\lambda z} \pi(\lambda z) + \lambda y(\lambda z)$$

Interpretation of the Sticky Information Phillips curve

- Output gap at freq z depends on output gap and inflation at dampened frequencies, λz
- λ introduces stickiness in the frequency domain: If the fraction of firms with an info update is low (high), output gap is driven more strongly by inflation at low (high) frequencies
- Output gap depends only on inflation at higher frequencies: vertical SIPK in the long run

Determinacy in the Frequency Domain

Continuation of analytic function over a removable singularity pins down initial condition

$$x_t = \alpha E_t x_{t+1} + \epsilon_t \quad \xrightarrow{z} \quad (1 - z \frac{1}{\alpha}) x(z) = x_0 - \frac{z}{\alpha}$$

If $|\alpha| < 1$, then for $z = \alpha$ there is a removable singularity inside the unit disk

$$\lim_{z \rightarrow \alpha} (1 - z \frac{1}{\alpha}) y(z) = 0$$

Sticky Price Determinacy

$$\begin{bmatrix} -\beta & 0 \\ \sigma & 1 \end{bmatrix} \begin{bmatrix} \pi(z) \\ y(z) \end{bmatrix} = \begin{bmatrix} -1 & \kappa \\ \sigma \phi_\pi & 1 + \sigma \phi_y \end{bmatrix} z \begin{bmatrix} \pi(z) \\ y(z) \end{bmatrix} + \begin{bmatrix} -\beta & 0 \\ \sigma & 1 \end{bmatrix} \begin{bmatrix} \pi_0 \\ y_0 \end{bmatrix}$$

Decoupling as follows gives two singularities $\lim_{z \rightarrow 1/\lambda_i} (1 - z \lambda_i) w_i(z) = 0$, $i = 1, 2$

$$[w_1(z) \ w_2(z)]' = V^{-1} [\pi(z) \ y(z)]'$$

- Singularities inside the unit circle if $1 - \frac{1-\beta}{\kappa} \phi_y < \phi_\pi$
- ⇒ Standard SP result, output gap targeting can substitute for inflation
- Taylor principle sufficient but **not necessary** for determinacy

Sticky Information Determinacy

$$\begin{bmatrix} \pi(z) \\ y(z) \end{bmatrix} = \begin{bmatrix} \phi_\pi & \frac{1+\sigma\phi_y-\lambda}{\sigma} \\ 0 & \lambda \end{bmatrix} z \begin{bmatrix} \pi(z) \\ y(z) \end{bmatrix} + \begin{bmatrix} \frac{1-\lambda\xi}{\lambda} & \frac{1}{\sigma} \\ 0 & 0 \end{bmatrix} y_0 + \begin{bmatrix} -\frac{\lambda}{\sigma\xi} & -\frac{\lambda(1-\lambda z)}{\sigma} \\ \frac{\lambda}{\xi} & \lambda(1-\lambda z) \end{bmatrix} \begin{bmatrix} \pi(\lambda z) \\ y(\lambda z) \end{bmatrix}$$

$x(\lambda z)$: **Irrelevant** for determinacy (a property of $x(z)|_{|z|=1}$)

- Backward looking (**recursive in frequency**) SI PK gives one initial condition $\xi \frac{1-\lambda}{\lambda} y_0 = \pi_0$
- Of the two eigenvalues (λ and ϕ_π , one and only one must provide a removable singularity to pin down remaining condition
 - As the probability of no information update, $0 < \lambda < 1$, certainly inside the unit circle
- Hence it **must** hold that $1 < \phi_\pi$
- ⇒ A stricter bound, output gap targeting cannot substitute for inflation
- Taylor principle sufficient and **necessary** for determinacy

Extension

Consider the more **general Taylor rule**

$$R_t = \rho_R R_{t-1} + (1 - \rho_R) [\phi_\pi (\alpha_\pi \pi_t + (1 - \alpha_\pi) E_t \pi_{t+1}) + \phi_y (\alpha_y y_t + (1 - \alpha_y) \Delta y_t)]$$

- $0 \leq \rho_R < 1$ allows for interest rate smoothing
- α_π : both contemporaneous ($\alpha_\pi = 1$) as well as future ($\alpha_\pi = 0$) inflation targeting
- α_y : output gap level ($\alpha_y = 1$) as well as output gap growth ($\alpha_y = 0$) targeting

The IS and Taylor rule in frequency representation

$$\begin{aligned} & [1 - (1 - \rho_R) \phi_\pi (1 - \alpha_\pi) - z(\rho_R (1 - \phi_\pi \alpha_\pi) + \phi_\pi \alpha_\pi)] \pi(z) \\ &= [1 - (1 - \rho_R) \phi_\pi (1 - \alpha_\pi) - z \rho_R] \pi(0) - \frac{1 - z \rho_R}{\sigma} y(0) \\ &+ \left[\frac{1}{\sigma} + \phi_y (1 - \rho_R) - z \left(\frac{1 + \rho_R}{\sigma} + \phi_y (1 - \rho_R) (1 - \alpha_y) \right) + z^2 \frac{\rho^2}{\sigma} \right] y(z) \end{aligned}$$

This posits a relation between $\pi(z)$ and $y(z)$

Sticky Price Determinacy Sticky Price Phillips curve

$$(1 - \beta \frac{1}{z} \pi(z) - \kappa y(z) = -\beta \frac{1}{z} \pi_0 + \kappa y(z)$$

- posits a long-run ($|z| = 1$) tradeoff between inflation and the output gap
- **fragile**, specification specific determinacy bounds
- Taylor principle not directly relevant

Sticky Information Determinacy

Sticky Information Phillips curve

$$y(z) = \frac{\lambda}{\xi} \frac{1}{1-\lambda z} \pi(\lambda z) + \lambda y(\lambda z) = \frac{1}{\xi} \sum_{j=1}^{\infty} \frac{\lambda^j}{1-\lambda^j z} \pi(\lambda^j z)$$

- **no** long-run ($|z| = 1$) tradeoff between inflation and the output gap
- Backward looking (**recursive in frequency**) SI PK gives one initial condition $\xi \frac{1-\lambda}{\lambda} y_0 = \pi_0$
- Removable singularity must be in the IS + Taylor rule wrt inflation

$$\lim_{z \rightarrow \omega} [1 - (1 - \rho_R) \phi_\pi (1 - \alpha_\pi) - z(\rho_R (1 - \phi_\pi \alpha_\pi) + \phi_\pi \alpha_\pi)] \pi(z) = 0$$

- Is relevant for determinacy if and only if

$$|\omega| = \left| \frac{1 - (1 - \rho_R) \phi_\pi (1 - \alpha_\pi)}{\rho_R (1 - \phi_\pi \alpha_\pi) + \phi_\pi \alpha_\pi} \right| < 1$$

- No amount or type of output targeting can replace necessary focus on inflation!

Sticky Information in the Frequency Domain

Sticky Information + z-transform

- Sticky Information Phillips Curve:
 - presents a **recursive representation in the time domain** (infinite regress)

- **z-transform:** transforms the model into the frequency domain

- allows for a closed form solution

Sticky Information in the Frequency Domain: **recursive representation of infinite regress** ✓
closed form solution ✓ ⇒ **new insights into monetary policy!**